

# MINIRANGER

## Unmanned Surface Vehicle

The Miniranger is a compact and effective unmanned vehicle created to perform autonomous underwater surveys, along with a wide range of other underwater tasks.

### MAIN TASKS:

- > Marine drone for underwater and minehunting missions
- > Security and surveillance
- > Search, localization and classification operations performed on areas being surveyed
- > Site survey performed using payloads sensors

The control station can be placed out of the operational area, on shore or aboard a support vessel. The system enables a significant reduction of personnel and operational costs and provides maximum safety even in harsh and dangerous areas.

### KEY FEATURES:

- > Hull-mounted payload including sidescan, sonar and multibeam sonar
- > Deployable payload including sidescan sonar (towed), mini ROV, current profilers, seawater samplers, magnetometers
- > Transportability by means of a standard 20 ft container
- > Remote-control panel, providing real-time data for real-time decision-making

TECHNICAL CHARACTERISTICS	
Dimensions:	Length: 4,5 m, Width: 2,5 m (1,5 deflated)
Propulsion:	Outboard 40 HP
Mass:	800 kg full loaded
Max draught:	0,8 m
Max speed:	18 kts
Autonomy:	(fully operational): 8 h
Operational range:	10 nm control, 5 nm media data
Basic equipment:	GPS, compass, echo-sounder, video-camera
Sonar depth:	100 m, with altitude control and obstacle avoidance



# 100 m

SONAR DEPTH

### Featuring:

- > GPS
- > Compass
- > Echo-sounder
- > Videocamera
- > Altitude control
- > Obstacle avoidance





## EQUIPMENT & OPERATIONAL MODES

The sea bottom images are transmitted to the remote-control station for recording and for the operator's real-time evaluation. On-board recording is also active. The towed sonar is automatically controlled at the optimal altitude from the sea bottom, with an obstacle avoidance feature.

The Miniranger supports three operational modes:

- > Manned
- > Remotely controlled
- > Semi-autonomous

The remote-control station comes with:

- > Mission workstation for vehicles management
- > Tactical workstation for payload management
- > Control panel for remote control performed by the operator



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### UNMANNED SURFACE VEHICLE

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This document consists of general capabilities information that is not defined as controlled technical data under ITAR Part 120.10 or EAR Part 772.

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