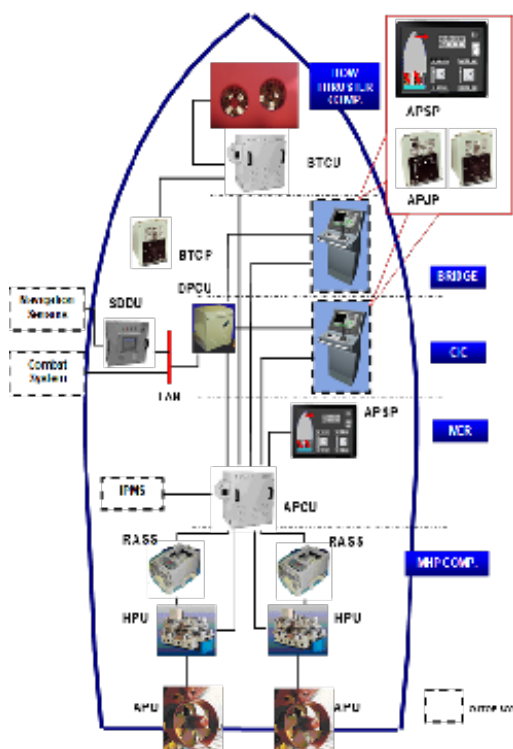


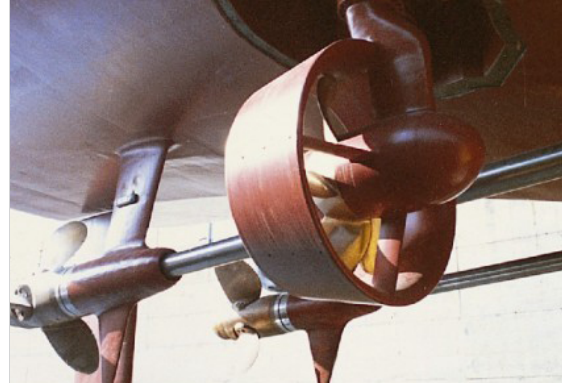
The minehunting propulsion system represents the ideal solution for the handling of dynamic positioning and auxiliary propulsion.

- > the propulsion group, including a retractable azimuthal hydraulically driven thruster, featuring both low noise and magnetic signature able to provide a 360° directable thrust.
- > the electrical twin bow thrusters, a single integrated unit inclusive of two fixed tunnel monodirectional thrusters with a bow thruster control unit (BTCU) and a joystick (BTCP) to provide a side thrust at the bow of the vessel.
- > the integrated control system (ICS), providing complete automation of the MHP plant and the dynamic positioning functions of the ship

- > two auxiliary retractable and azimuthal thrusters and one twin bow thruster
- > three auxiliary retractable and azimuthal thrusters

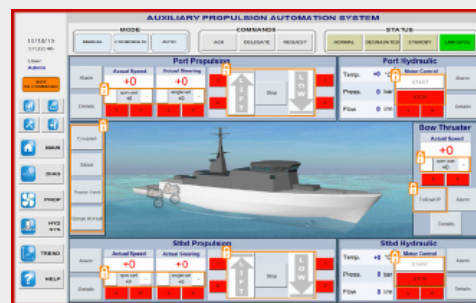


- > Auxiliary propulsion status panel (APSP), an operator panel for individual control of the auxiliary thrusters
- > Auxiliary propulsion joystick panel (APJP), consisting in a joystick and a knob, enabling the coordinate control of the auxiliary propulsion.
- > Dynamic positioning control unit (DPCU), performing the dynamic positioning of the vessel using the auxiliary propulsion
- > Auxiliary propulsion control unit (APCU), performing the complete control and monitoring of the minehunting propulsion
- > Smart data distribution unit (SDDU), which collects, processes and distributes navigation data provided by the sensors
- > Remote auxiliary soft starter (RASS), an electronic unit performing the starting of the electric motor of the HPU reducing the peak of the starting current



**ACTIONABLE
INTELLIGENCE**

- > Autopilot mode
- > Enhanced ship maneuverability
- > Low magnetic signature
- > Low acoustic signature
- > Underwater explosion resistance

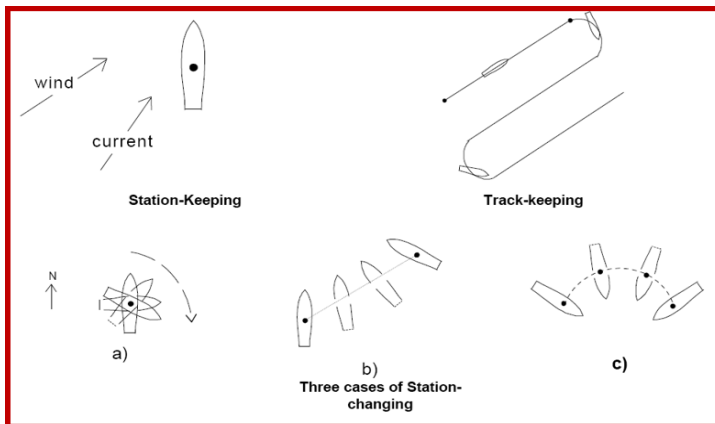


AUXILIARY PROPULSION STATUS PANEL

The DPCU includes the minehunting autopilot, an high performance dynamic positioning system for MCMVs vessels and special ships. The system is able to achieve precise ship handling on specified trajectories or hovering points, performing sea areas surveillance.

KEY FEATURES:

- > Dedicated LAN interface for connection to IPMS. Major failure signals can be uplicated using hard wiring.
- > Fiber optics communication with command and control for high disturbs immunity
- > Redundant CAN open communication with APJP
- > Redundant power supply with automatic switch in case of failure
- > Easy-to-use and intuitive thrusters



AUTOPILOT OPERATIONAL MODES



SMART DATA DISTRIBUTION UNIT

APSP TECHNICAL CHARACTERISTICS:

- > Power Supply: 110/240 Vac, 50/60 Hz
- > Power consumption: c.a. 250 W
- > Redundant fiber optics communication
- > Certified with:
MIL-STD 461-F for EMI/EMC
MIL-STD-167-1:1987 type I for vibration
MIL-S-901D:1989, classified as grade A, class I, type A for shock
- > Dimming: from 0 to 100% of luminous intensity
- > Enclosure: IP 54
- > Temperature range: 0°C + 45°C (32°F +113°F)



Minehunting Propulsion And Control System

COMPLETE PROPULSION SYSTEM
FOR MINEHUNTING VESSELS

This document consists of general capabilities information that is not defined as controlled technical data under ITAR Part 120.10 or EAR Part 772.

Minehunting Propulsion And Control System

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